Universes of data types in constructive type theory Lecture 2: Inductive data types, generically

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### Examples of inductive definitions Martin-Löf (1972, 1979, 1980, ...)

We have seen examples of inductive definitions such as  $\ensuremath{\mathbb{N}}$  and lists.

Similarly the first accounts of Martin-Löf type theory included specific inductive definitions:

- ▶ N, finite sets (1972)
- ▶ W-types (1979)
- ▶ Kleene's *O*, lists (1980)

The system is considered open; new inductive types should be added as needed.

"We can follow the same pattern used to define natural numbers to introduce other inductively defined sets. We see here the example of lists." – Martin-Löf 1980

Pfenning and Paulin-Mohring (1989)

 First attempt in Calculus of Constructions: use Church encodings of inductive types.

► E.g.

$$\mathbb{N} := (X : \mathsf{Type}) \to X \to (X \to X) \to X$$

$$a =_A b := (X : A \to \mathsf{Type}) \to X(a) \to X(b)$$

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- Problems:
  - Uses impredicativity in an essential way.
  - Induction (dependent elimination) is not derivable in CoC for any encoding [Geuvers 2001]. (Can be corrected using a refined construction; see Awodey, Frey and Speight [2018].)

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- Solution: Calculus of Inductive Constructions with inductive types builtin (according to schema).

## Syntactic schemata

Backhouse (1987), Coquand and Paulin-Mohring (1990), Dybjer (1994), ...

Dybjer (1994) considers constructors of the form

$$\mathsf{intro}_D:(A::\sigma)\ (b::eta[A])
ightarrow\ (u::\gamma[A,b])
ightarrow\ D$$

where

- σ is a sequence of types for parameters ['x :: Y' telescope notation]
- $\beta[A]$  is a sequence of types for non-inductive arguments.
- $\gamma[A, b]$  is a sequence of types for inductive arguments:
  - Each  $\gamma_i[A, b]$  is of the form  $\xi_i[A, b] \to D$  (strict positivity).

Syntactic schemata (cont.)

- The elimination and computation rules are determined by an inversion principle.
- Infinite axiomatisation.
- ▶ Inprecise; '....' everywhere.
- No way to reason about an arbitrary inductive definition *inside* the system (generic map etc.).

## Syntax internalised

Dybjer and Setzer (1999, 2003, 2006) [for IR], Morris, Altenkirch and McBride (2007) ...

- Setzer wanted to analyse the proof-theoretical strength of Dybjer's schema version of induction-recursion.
- Hard with lots of '...' around...
- So they developed an axiomatisation where the syntax has been internalised into the system.
- Basic idea (simplified for inductive definitions) : the type is "given by constructors", so describe the domain of the constructor

$$\mathsf{intro}_{D_\gamma}:\mathsf{Arg}(\gamma,D_\gamma)\to D_\gamma$$

[  $\gamma$  is "code" that contains the necessary information to describe  $D_{\gamma}.]$ 

### Basic idea in some more detail

- Universe SP of codes for the domain of constructors of inductively defined sets. [SP stands for Strictly Positive.]
- Decoding function Arg : SP → Type → Type. [Arg(γ, X) is the domain where X is used for the inductive arguments.]
- For every γ : SP, stipulate that there is a set D<sub>γ</sub> and a constructor intro<sub>γ</sub> : Arg(γ, D<sub>γ</sub>) → D<sub>γ</sub>.
- Calculate types for elimination and computation rules.

Underlying type theory ("logical framework")

We assume we have the following types:

- Dependent function types  $(x : A) \rightarrow B$
- Dependent pair types  $(x : A) \times B$
- A unit type 1, and a type of Booleans Bool
- (For future use: identity types  $a =_A a'$ )

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The rest we will add generically!

## Idea for SP

Inductive types are determined by their constructors, so analyse possible constructors.

For example:

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Constructor for well-founded trees W S P:

$$\sup: (s:S) \to (f:P[s] \to WSP) \to WSP$$

## The universe SP of codes

Fix two universes  $(U_{sc}, T_{sc})$  and  $(U_{ar}, T_{ar})$ . We will draw side conditions (non-inductive arguments) and arities of inductive arguments from these.

Formation

SP type

Introduction

done : SP

$$\frac{A: U_{sc} \qquad \gamma: T_{sc}(A) \to \mathsf{SP}}{\operatorname{nonind} A\gamma: \mathsf{SP}} \qquad \frac{A: U_{ar} \qquad \gamma: \mathsf{SP}}{\operatorname{ind} A\gamma: \mathsf{SP}}$$

Elimination, computation ...

By changing  $U_{sc}$  and  $U_{ar}$ , we can restrict to different subclasses of inductive definitions.

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Discrete types:

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Discrete types:

•  $U_{sc} = \{ \text{discrete types} \}, U_{ar} = \{ \text{unit type} \}$ 

Propositional types:

▶ U<sub>sc</sub> = {propositional types}, U<sub>ar</sub> = {arbitrary types}

Finite types:

And so on.

## Arg and $D_{\gamma}$

Codes are given their meaning by  $\mathsf{Arg}:\mathsf{SP}\to\mathsf{Type}\to\mathsf{Type}.$ 

$$Arg \text{ done } X \equiv \mathbf{1}$$

$$Arg (\text{nonind } A\gamma) X \equiv (y : T_{sc}(A)) \times (Arg (\gamma y) X)$$

$$Arg (\text{ind } A\gamma) X \equiv (T_{ar}(A) \rightarrow X) \times (Arg \gamma X)$$

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One generic inductive definition (parametrised by  $\gamma$ ): Formation

$$\frac{\gamma:\mathsf{SP}}{D_{\gamma}\;\mathsf{type}}$$

Introduction

$$\frac{x:\operatorname{Arg}\gamma\,D_{\gamma}}{\operatorname{intro}_{\gamma}x:D_{\gamma}}$$

### Multiple constructors

Assuming  $U_{sc}$  contains Bool, we can encode two constructors into one:

$$\gamma +_{\mathsf{SP}} \psi \coloneqq \mathsf{nonind}(\mathsf{Bool}, \lambda x. \text{ if } x \text{ then } \gamma \text{ else } \psi)$$

The point being:

 $\operatorname{Arg} (\gamma +_{\operatorname{SP}} \psi) X \cong (\operatorname{Arg} \gamma X) + (\operatorname{Arg} \psi X)$ and  $(A + B \to C) \cong (A \to C) \times (B \to C).$ 

We have

 $\gamma_{\text{List }A} \equiv \text{done} +_{\text{SP}} \text{nonind}(A, \lambda_{-}.ind(\mathbf{1}, \text{done}))$ 

with List  $A \equiv D_{\gamma_{\text{List }A}}$ .

[] : List A $[] \equiv ?_0 : D_{\gamma_{\text{List } A}}$ 

 $\begin{array}{l} \_ :: \_ : A \to \mathsf{List} \, A \to \mathsf{List} \, A \\ x :: xs \equiv \boxed{?_1 : D_{\gamma_{\mathsf{List}} \, A}} \end{array}$ 

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[] : List A []  $\equiv intro_{\gamma_{\text{List }A}}$  ?<sub>2</sub> : (x : Bool) × (if x then **1** else  $A \times (\mathbf{1} \rightarrow \text{List }A) \times \mathbf{1}$ )

 $\begin{array}{l} \vdots \vdots \vdots \vdots \vdots : A \to \operatorname{List} A \to \operatorname{List} A \\ x :: xs \equiv \begin{array}{l} ?_1 : D_{\gamma_{\operatorname{List} A}} \end{array}$ 

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Hence we define

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lifting  $P: X \rightarrow$  Type to substructures:

All done  $P_{-} \equiv \mathbf{1}$ All (nonind  $A\gamma$ )  $P(a, y) \equiv All (\gamma a) P y$ All (ind  $A\gamma$ )  $P(g, y) \equiv ((x : T_{ar} A) \rightarrow P(g x)) \times All \gamma P y$ 

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every : 
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**Exercise:** Can you make sense of All as a functor in the conventional sense? What categories are involved?

# Elimination and computation rules



## Elimination and computation rules



#### Elimination

$$\frac{z: D_{\gamma} \vdash C \text{ type } x: \operatorname{Arg} \gamma D_{\gamma}, \bar{x}: \operatorname{All} \gamma C x \vdash d: C[z \mapsto \operatorname{intro}_{\gamma} x] \quad p: D_{\gamma}}{\operatorname{elim}_{\gamma}(C, d, p): C[z \mapsto p]}$$

#### Computation

 $\mathsf{elim}_{\gamma}(\mathcal{C}, d, \mathsf{intro}_{\gamma} a) \equiv d[x \mapsto a, \bar{x} \mapsto \mathsf{every} \, \gamma \, (\mathsf{elim}_{\gamma}(\mathcal{C}, d))] : \mathcal{C}[z \mapsto \mathsf{intro}_{\gamma} a]$ 

Hence  $\operatorname{Arg} \gamma_{\mathbb{N}} X \cong \mathbf{1} + X$ .

We define  $0 := \operatorname{intro}_{\gamma_{\mathbb{N}}} (\operatorname{inl} \star)$  and suc  $n := \operatorname{intro}_{\gamma_{\mathbb{N}}} (\operatorname{inr} n)$ .

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Further

 $\operatorname{All} \gamma_{\mathbb{N}} P \, 0 = \mathbf{1}$  $\operatorname{All} \gamma_{\mathbb{N}} P \, (\operatorname{suc} n) \cong P \, n$ 

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Further

$$\mathsf{AII}\,\gamma_{\mathbb{N}}\,P\,\mathsf{0} = \mathbf{1}$$
$$\mathsf{AII}\,\gamma_{\mathbb{N}}\,P\,(\mathsf{suc}\,n) \cong P\,n$$

As expected, the "step function"

 $x : \operatorname{Arg} \gamma D_{\gamma}, \overline{x} : \operatorname{All} \gamma C x \vdash d : C[z \mapsto \operatorname{intro}_{\gamma} x]$ 

thus splits up into  $d_0: C[z \mapsto 0]$  and

$$n: \mathbb{N}, \bar{n}: C[z \mapsto n] \vdash d_{\mathsf{suc}}: C[z \mapsto \mathsf{suc} n]$$

and we recover the usual induction principle.

# Does it make sense?

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Good first candidate: "naive" set-theoretic model.

Let us work in the closed-types-as-sets model:

$$\llbracket (x : A) \to B \rrbracket = \prod_{x \in \llbracket A \rrbracket} \llbracket B \rrbracket$$
$$\llbracket (x : A) \times B \rrbracket = \sum_{x \in \llbracket A \rrbracket} \llbracket B \rrbracket$$
$$\llbracket 1 \rrbracket = \{ \star \}$$
$$\llbracket Bool \rrbracket = \{ 0, 1 \}$$
$$\llbracket a =_A a' \rrbracket = \{ \star \mid \llbracket a \rrbracket = \llbracket a' \rrbracket \}$$

2

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:

Ind. definitions represented by monotone operators  $\Gamma$ : Set  $\rightarrow$  Set. For example:  $\Gamma_{\mathbb{N}}(X) = \{0\} \cup \{ \text{suc } n \mid n \in X \}.$ 

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Ind. definitions represented by monotone operators  $\Gamma$  : Set  $\rightarrow$  Set. For example:  $\Gamma_{\mathbb{N}}(X) = \{0\} \cup \{ \text{suc } n \mid n \in X \}$ . Inductive definition  $I(\Gamma)$  interpreted as the result of iterating  $\Gamma$ :

$$\emptyset \subseteq \Gamma(\emptyset) \subseteq \Gamma^2(\emptyset) \subseteq \ldots$$

Let us work in the closed-types-as-sets model:

$$\llbracket (x : A) \to B \rrbracket = \prod_{x \in \llbracket A \rrbracket} \llbracket B \rrbracket$$
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**More work:** Say  $\Gamma$  is  $\kappa$ -based for cardinal  $\kappa$  if  $x \in \Gamma(X)$  implies  $x \in \Gamma(Y)$  for some  $Y \subseteq X$  with  $|Y| < \kappa$ . (cf. Aczel 1977)

**Example:**  $\Gamma_{\mathbb{N}} = X \mapsto \{0\} \cup \{\text{suc } n \mid n \in X\}$  is 2-based.

**Thm:** If  $\Gamma$  is  $\kappa$ -based for a regular  $\kappa$ , then  $I(\Gamma) = \Gamma^{\kappa}$ .

## Soundness of SP

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Hence  $I(\operatorname{Arg} \gamma)$  exists.

The elimination principle can be interpreted using that  $I(\operatorname{Arg} \gamma)$  is the least fixed point.

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With a universe of inductive definitions, we have

Generic programming = Programming

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Generic programming = Programming

A more high-level language with data declarations etc can be elaborated to codes using the universe of inductive definitions.

## Example: decidable equality

Let us implement deriving Eq.

Rather than just saying yes or no, let us also produce evidence that  $Dec(x =_A y) := (x =_A y) + (x \neq_A y).$ 

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We mutually define

 $\begin{array}{l} \mathsf{eq}: (\gamma:\mathsf{SP}) \to (x:D_{\gamma}) \to (y:D_{\gamma}) \to \mathsf{Dec}\,(x=y) \\ \mathsf{eqArg}: (\gamma,\gamma':\mathsf{SP}) \to (x:\mathsf{Arg}\,\gamma\,D_{\gamma'}) \to (y:\mathsf{Arg}\,\gamma\,D_{\gamma'}) \to \mathsf{Dec}\,(x=y) \end{array}$ 

```
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                                                                                          \sim \sim \otimes
File Edit Options Buffers Tools Aqda Help
open import Data.Product
open import Data.Product.Properties
open import Data.Unit
open import Relation.Nullary
open import Relation.Binary.PropositionalEquality
open import Axiom.UniquenessOfIdentityProofs
module decEq (U : Set)(T : U → Set)
                (dec : (A : U) \rightarrow (x v : T A) \rightarrow Dec (x \equiv v)) where
-- universe containing unit type only
TT : T → Set
TT = T
-- Because of uniqueness for T and functions, we can prove funext for
-- functions out of T
funextT : {A : Set} \rightarrow {f q : T \rightarrow A} \rightarrow f tt \equiv q tt \rightarrow f \equiv q
funextT {A} {f} {a} = lem {A} {f tt} {a tt}
  where
    lem : {A : Set} \rightarrow {ftt att : A} \rightarrow ftt = att \rightarrow (\lambda (x : T) \rightarrow ftt) = (\lambda x \rightarrow att)
    lem refl = refl
open import SP U T T TT
mutual
   eqArg : \{s' : SP\}(s : SP) \rightarrow (x y : Arg s (D s')) \rightarrow Dec (x \equiv y)
   eqArq done x y = yes refl
   eqArg (non-ind A s) (a , x) (a' , y) with dec A a a'
   egArg (non-ind A s) (a , x) (a , v) | ves refl with egArg (s a) x v
   eqArg (non-ind A s) (a , x) (a , y) | yes refl | yes x≡y =
     ves (cong (a , ) x=v)
   eqArg (non-ind A s) (a , x) (a , y) | yes refl | no ¬x≡y =
     no \lambda r \rightarrow \neg x \equiv y (,-injective'-= (Decidable \rightarrow UIP = -irrelevant (dec A)) r refl)
   eqArg (non-ind A s) (a , x) (a' , y) | no ¬p =
     no \lambda ax=a'y \rightarrow \neg p (cong proji ax=a'y)
   eqArg {s'} (ind A s) (f, x) (g, y) with eq s' (f) (g) | eqArg s x y
   ... | yes p | yes q = yes (conq_2), (funextT p) q)
   ... | ves p | no q = no \lambda r \rightarrow q (conq proj<sub>2</sub> r)
   ... | no p | q = no \lambda r \rightarrow p (cong (\lambda h \rightarrow h tt) (cong proj_1 r))
  eq : (s : SP) \rightarrow (x y : D s) \rightarrow Dec (x \equiv y)
  eq s (inn x) (inn y) with eqArg s x y
  ... | yes p = yes (cong inn p)
   ... | no \neg p = no (\lambda innx=inny \rightarrow \neg p (inn-inj innx=inny))
.
∏U:--- decEq.aqda
                            All L47 (Agda:Checked)
□U:%*- *All Done* All L1
                                       (AgdaInfo)
```

# Summary

Generic treatment of inductive definitions in type theory using a universe of data types.

Can be given set-theoretic semantics using iteration of monotone operators.

In type theory, "Generic programming" = "Programming".